


```

BOTA      VSS      0      I =      -3m*tanh((V(IN)-V(VOUT))*10)
RBP       VSS      VIN     5k
CBW       VIN      0       30p
Rout      VOUT     0       100
.model    NPN1     NPN(   BF=510 VAF=916 tf=100n  CJE=150p CJC=500p CJS=500p )
.model    PNP1     PNP(   BF=510 VAF=216 tf=1u    CJE=150p CJC=500p CJS=500p )

```

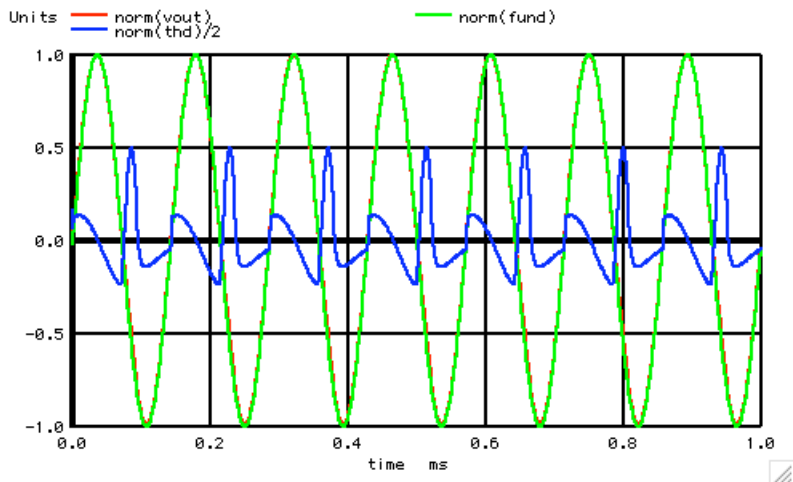
*=====Extract_the_Distortion=====

The FFT and IFFT functions allow the fundamental to be removed to view the distortion along side the output signal.

```

=====
.control
*TRAN      TSTEP  TSTOP  TSTART  TMAX    ?UIC?
tran       1u     .999m  0       1u
set        pensize = 2
linearize
let        numb2 = length(vin)
print      numb2
let        t_inde2 = vector($&numb2)
let        ac = vout +j(0)
let        ac_fft=fft(ac)
plot       real(ac_fft) imag(ac_fft) vs t_inde2
let        funBin = VFreq[0]/1000
let        unvect = unitvec($&numb2)
let        fundspec = unvect*0 +j(0)
let        fundspec[funBin] = real(ac_fft[funBin]) +j(imag(ac_fft[funBin] ))
let        fundspec[numb2-funBin] = real(ac_fft[numb2-funBin]) +j(imag(ac_fft[numb2-funBin] ))
let        fund = ifft(fundspec)
let        dc_offset = real(ac_fft[0])
let        thdspec = ac_fft
let        thdspec[0] = 0 +j(0)
let        thdspec[funBin] = 0 +j(0)
let        thdspec[numb2-funBin] = 0 +j(0)
let        thd = ifft(thdspec)
plot       norm(vout) norm(fund) norm(thd)/2

```



*=====Calculate_the_Distortion=====

To put things into perspective, finding out what the actual distortion level is, determines what gets done about it.

```

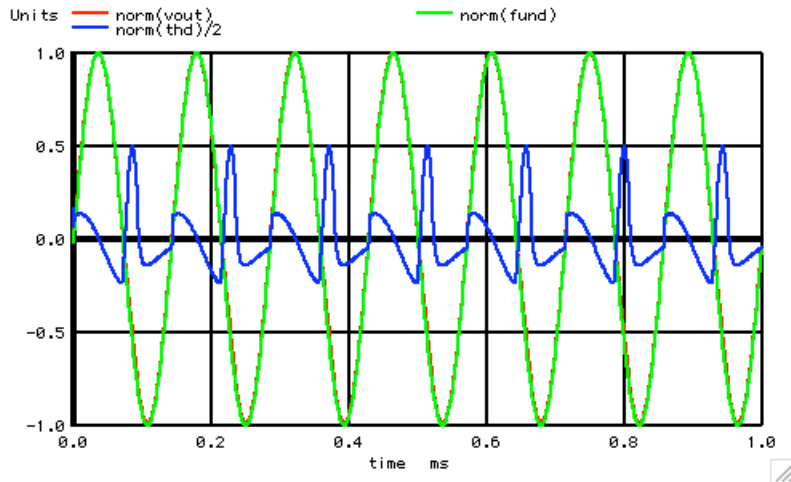
=====
let        rms_Fund = sqrt(mean(fund*fund))
let        rms_THD = sqrt(mean(thd*thd))
let        THD_percent = 100*rms_THD/rms_Fund
let        FREQ_Hz = VFreq[0]
echo       "Freq_Hz=$&FREQ_Hz THD_percent=$&THD_percent DC=$&dc_offset"
=====

```

Freq_Hz=8000 THD_percent=4.2893 DC=0.105696

*=====What_does_4%_distortion_mean=====

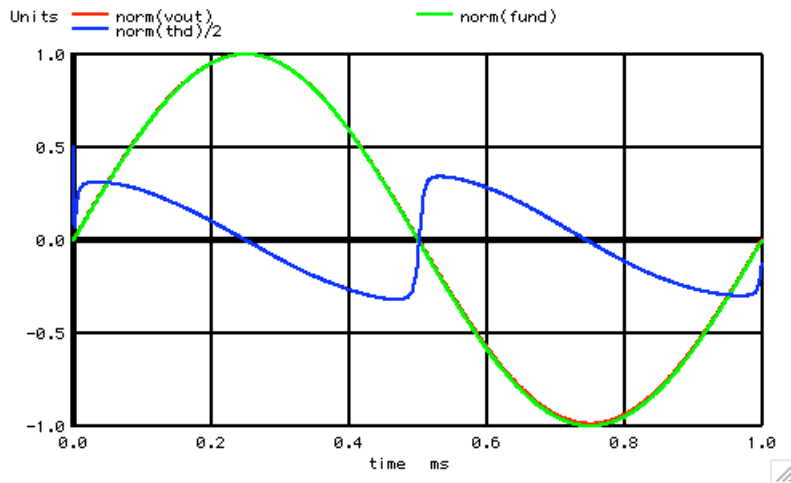
If one is young, one might be able to hear the distortion of a 8KHz signal. But usually the distortion gets reduced to make pretty distortion plot.



*=====Distortion_is_frequency_dependent=====

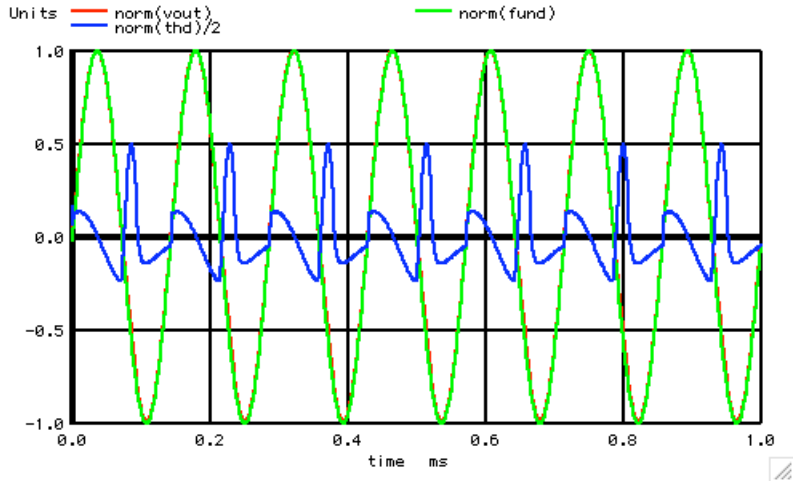
At 1kHz, the distortion is 42 times lower than at 8Khz. Different parts of an audio power amplifier require attention to distortion at different frequencies.

=====
Freq_Hz=1000 THD_percent=0.101815 DC=0.0310647



*=====The_distortion_waveform=====

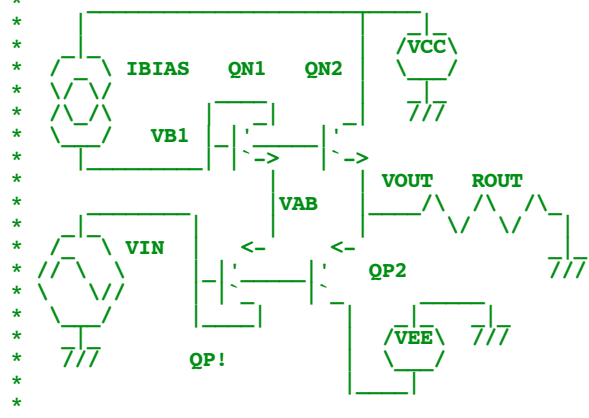
The distortion wave form shows where a transistor is working hard. For audio power amplifiers like the LM383, there is a tradeoff in output distortion versus supply current. Running an output more B bias will increase distortion, but lower supply current. While power amplifiers can put out several amps, having the lowest supply current as possible can sell the amplifier.



The distortion waveform provides the ability to do cause and effect analysis on a circuit design. Making it possible to see when the distortion happens, it is not real hard to find something going on inside a circuit design which is happening at the same time. Not having to guess is a real time saver.

=====Full_Netlist_For_Copy_Paste=====

Output_THD



```

VCC      VCC      0      DC      10
VEE      VEE      0      DC      -10
VTime    VTime    0      DC      0      PWL( 0 0 1 1)
Vfreq    Vfreq    0      DC      1k
BVAC     IN       0      V      = 5*sin( 6.283185307179586*(V(Vfreq))*V(VTime))
QN1      VB1      VB1      VAB      NPN1      1
QN2      VCC      VB1      VOUT     NPN1      1
QP1      VIN      VIN      VAB      PNP1      1
QP2      VEE      VIN      VOUT     PNP1      1
IBIAS    VCC      VB1      900u
BOTA     VSS      0      I      = -3m*tanh((V(IN)-V(VOUT))*10)
RBP      VSS      VIN      5k
CBW      VIN      0      30p
Rout     VOUT     0      100
.model  NPN1    NPN(  BF=510 VAF=916 tf=100n  CJE=150p CJC=500p CJS=500p )
.model  PNP1    PNP(  BF=510 VAF=216 tf=1u    CJE=150p CJC=500p CJS=500p )

```

```

.control
*TRAN  TSTEP  TSTOP  TSTART  TMAX  ?UIC?
tran    1u     .999m  0       1u
set     pensize = 2
linearize
let     numb2 = length(vin)

```

```

print      numb2
let      t_indx2 = vector($&numb2)
let      ac = vout +j(0)
let      ac_fft=fft(ac)
plot      real(ac_fft) imag(ac_fft) vs t_indx2
let      funBin      = VFreq[0]/1000
let      unvect      = univec($&numb2)
let      fundspec    = unvect*0 +j(0)
let      fundspec[funBin] = real(ac_fft[funBin])      +j(imag(ac_fft[funBin] ))
let      fundspec[numb2-funBin] = real(ac_fft[numb2-funBin]) +j(imag(ac_fft[numb2-funBin] ))
let      fund        = ifft(fundspec)
let      dc_offset   = real(ac_fft[0])
let      thdspec     = ac_fft
let      thdspec[0]   = 0      +j(0)
let      thdspec[funBin] = 0      +j(0)
let      thdspec[numb2-funBin] = 0      +j(0)
let      thd         = ifft(thdspec)
plot      norm(vout) norm(fund) norm(thd)/2

let      rms_Fund    = sqrt(mean(fund*fund))
let      rms_THD     = sqrt(mean(thd*thd))
let      THD_percent = 100*rms_THD/rms_Fund
let      FREQ_Hz     = VFreq[0]
echo      "Freq_Hz=$&FREQ_Hz THD_percent=$&THD_percent DC=$&dc_offset"

.endc
.end

```